

Simultaneous Optimal Placement and Sizing of DSTATCOM and Parallel Capacitors in Distribution Networks Using Multi-Objective PSO

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Abstract—The increase in electricity demands has increased the dimension and loading of today radial distribution feeders, which in turn would result in more losses and voltage drops. Such issues together with the demand for higher power quality has raised a need for modern power system management techniques such as using power electronic devices. Among, DSTATCOM is introduced as an effective solution for reactive power control in power distribution level. To make a better use of DSTATCOM in improving the network power quality, it should be sized and placed in accordance with parallel capacitors. A multi-objective optimization method is proposed in this paper to find the optimal location and size of DSTATCOM and parallel capacitors simultaneously. The cost of power losses, voltage profile and voltage stability are selected as objectives to be improved. The obtained results on the IEEE 33-node test system indicate that the proposed method satisfies the defined objectives and considerably improves the network operational characteristics.

Index Terms—Distribution system, DSTATCOM, MOPSO, Optimization, Parallel capacitors.

I. INTRODUCTION

The increased demand for electricity has increased the loading and the size of today distribution networks. Considering the radial nature of distribution feeders, the increase in loading results in more voltage drop and power losses. Consequently, a large portion of power system losses are from the distribution level. Leveraging new technologies to improve voltage profile of power systems avoids load shedding which is techno-economically undesired [1].

The development in fast and reliable semiconductor switching devices and the advances in power electronics has led to an increase in their integration in all levels of today power systems. Among, DSTATCOM (Distribution Static Compensator) can provide a cost-effective solution for compensation of reactive power and improving the power quality of electrical power distribution systems. DSTATCOM

is a voltage source converter (VSC)-based power electronic device, supported by short-term energy stored in a dc capacitor [2]. It mainly consists of a DC energy storage device, a VSC that converts the dc voltage across the storage device into three-phase AC output, a controller and a coupling transformer.

If properly utilized, DSTATCOM can cancel the effect of poor load power factor, the effect of harmonic contents in loads, the effect of unbalanced loads and the dc offset in loads [2]. Optimal placement and sizing of DSTATCOM considerably influences its success in fulfilling the mentioned tasks. Therefore, some previous studies have considered this problem and have proposed solutions.

The method proposed in [3] considers the reduction in power losses and line currents together with the voltage profile as the objective function and use an immune algorithm to search for the optimal DSTATCOM placement. In [4] authors employ a Fuzzy-ACO algorithm for simultaneous reconfiguration, optimal placement of DSTATCOM, and photovoltaic array in a distribution system. The authors of [5]-[8] also propose methods for optimal sizing and placement for distributed generation units and DSTATCOM in a distribution network.

The Firefly algorithm is employed in [9] to find the optimal location of DSTATCOM to decrease power losses and harmonic distortions and to improve voltage levels. Analytical approaches are proposed in [10],[11] to solve the optimal placement problem. In [12] authors propose the use of a hybrid Genetic and Ant Colony algorithm to reduce network losses. The authors of [13] solve the DSTATCOM allocation problem considering network reconfiguration using a combination of BB-BC and Genetic algorithms. In [14] a Bat algorithm is employed to find the optimal location considering network loads variations. Despite the various previous research works performed for optimal placement of DSTATCOM, none of these studies consider the simultaneous

optimal placement and sizing of DSTATCOM and parallel capacitors in distribution networks [15].

Optimal placement and sizing of DSTATCOM in accordance with parallel capacitors, considerably influences its success in improving the network power quality. Parallel capacitors cannot provide a flexible compensation considering the variation in distribution system loads. On the other hand, DSTATCOM requires much more investment. Therefore, a combination of parallel capacitors and a limited number of DSTATCOM units can provide the required flexibility with an affordable cost.

In this paper, the cost of power losses, voltage profile and voltage stability are selected as objectives. Our studies show that the simultaneous placement and sizing of capacitors and DSTATCOM can considerably improve the considered objective functions. A MOPSO (Multi-Objective Particle Swarm Optimization) is employed to solve the problem and the tests performed on the IEEE 33-node test system verify the effectiveness of the proposed method.

II. PROBLEM FORMULATION

In this paper, three technical objectives are considered for DSTATCOM sizing and placement: lower power losses, better voltage profile and improved voltage stability. Therefore, the considered objective function is a multi-objective function:

$$\min F = [f_1, f_2, f_3] \quad (1)$$

The objective function f_1 is defined as:

$$f_1 = P_{loss} \quad (2)$$

where P_{loss} denotes the active power losses.

The objective function f_2 is a voltage deviation index defined as:

$$f_2 = \sum_{i=1}^N (V_i - V_{rated})^2 \quad (3)$$

where N is the number of network node.

The objective function f_3 is a voltage stability index proposed in [16]. The equations for evaluation of this index are based on power flow [17]. Consider the simple 2-node network of Fig. 1. The stability index for this simple feeder can be calculated as follows:

$$SI(n_2) = |V_1|^4 \left[4[P_2 R_1 + Q_2 X_1] |V_1| - 4[P_2 R_1 + Q_2 X_1]^2 \right] \quad (4)$$

where n_1, n_2, V_1, V_2 are sending and receiving nodes and their voltages respectively, P_2 and Q_2 are node 2 net active and reactive power, R_l and X_l are line resistance and reactance and I_L is the line current.

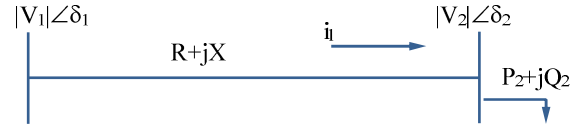


Figure 1. A distribution network branch

Considering the voltage stability index equation, the objective function f_3 is defined as:

$$f_3 = \frac{1}{f_3'} \quad (5)$$

$$f_3' = \min(SI(n_i)), i = 1, 2, \dots, N$$

where N is the number of network nodes.

A. DSTATCOM constraints

The considered constraints for DSTATCOM are as follows:

$$0.9 pu \leq V_n \leq 1.1 pu \quad (6)$$

$$0 \leq Q_{DSTATCOM} \leq 5000 KVAR \quad (7)$$

$$0 \leq I_{max} \leq 400 A \quad (8)$$

where $Q_{DSTATCOM}$ and I_{max} are the DSTATCOM reactive power and the maximum current of network branches.

B. Capacitors constraints

In practice, the parallel capacitors are composed of a group of several identical capacitors interconnected. Therefore, the capacity of a parallel capacitor is an integral multiple of a minimum base value:

$$Q_{ci} = L Q_0 \quad (9)$$

where Q_0 is the minimum base capacitance.

Due to economic considerations, the overall capacitance of the capacitors connected to a node is also limited:

$$\sum Q_{ci} \leq Q_t \quad (10)$$

where Q_t is the reactive power limit.

In this paper the considered minimum base capacitance is 150 KVAR and the maximum considered number of capacitances at each node is 15.

III. DSTATCOM LOAD FLOW MODEL

In this paper, the well-known backward forward sweep method is employed for distribution load flow. For the simple

two node network of Fig. 2, the following equation can be written:

$$V_j \angle \alpha = V_i \angle \delta - Z I_L \angle \theta \quad (11)$$

where, as shown in Fig. 2, V_i , V_j , α and δ are the voltages and their phase angles at the beginning and the end of the line-section, respectively. Z is the line impedance, I_L is the line current and θ denotes its phase angle.

After installation of the DSTATCOM at node j , as shown in the phasor diagram of Fig. 3, the equations change to the following form:

$$V_{j_{new}} \angle \alpha_{new} = V_i' \angle \delta' - (R + jX) I_L' \angle \theta' \quad (12)$$

$$(R + jX) I_{DSTATCOM} \angle (\alpha_{new} + \pi/2)$$

Therefore, the injected reactive power can be calculated as follows:

$$jQ_{DSTATCOM} = V_{j_{new}} I_{DSTATCOM} \quad (13)$$

$$\angle I_{DSTATCOM} = \frac{\pi}{2} + \alpha_{new}, \alpha_{new} < 0 \quad (14)$$

where α_{new} is the modified phase angle of the compensated node, which will be calculated using the above equations in load flow iterations [18].

A. Optimization algorithm

Particle swarm optimization (PSO) is a population based stochastic optimization algorithm inspired by sociological behavior associated with bird flocking or fish schooling. The PSO is comprised of a set of particles moving around the search space where the position of each particle is adjusted according to its own experience and that of its neighbors. Let f_i and x_i denote the objective function and the position of particle i in the search space changing with velocity v_i . The particle's personal best position denoted by $x_i^{i,best}$ refers to the position with the best value of the objective function $f_i^{i,best}$. The best position found over the whole swarm $x_g^{g,best}$ can be found by comparing all the $f_i^{i,best}$ for all particles. Let $f_g^{g,best}$ denote the objective function for $x_g^{g,best}$.

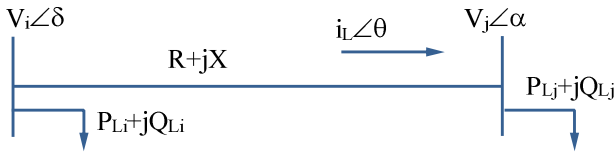


Figure 2. A simple two node network

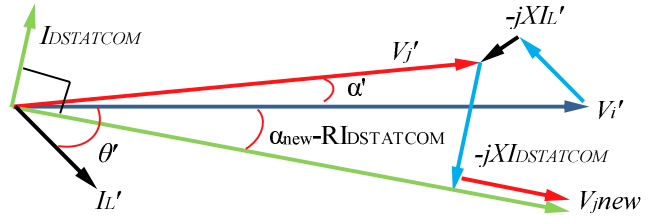


Figure 3. Phasor diagram after DSTATCOM installation

The positions and velocities of particles are initialized randomly. As the algorithm proceeds, at each step $t+1$, the velocities and positions are updated using the previous step values as follows:

$$v_j^i[t+1] = w v_j^i[t] + c_1 r_1 (x_j^{i,best}[t] - x_j^i[t]) + c_2 r_2 (x_j^{g,best}[t] - x_j^i[t]) \quad (15)$$

$$x_j^i[t+1] = x_j^i[t] + v_j^i[t+1] \quad (16)$$

where w is the inertia coefficient r_1 and r_2 are random values in the range $[0, 1]$ with uniform distribution and c_1 and c_2 are positive acceleration constants.

B. MOPSO algorithm

The multi-objective PSO proposed in 2004, is employed for simultaneous optimization of multiple objective functions [19]. In this algorithm, the vector x^* is Pareto optimal if there is no other feasible vector which would decrease some criterion without causing an increase in other criterions. The set of optimal solutions of the MOPSO composed of non-dominated solutions is known as the Pareto front. The vector x_1 is said to dominate x_2 (denoted by $x_1 \leq x_2$), if x_1 is not worse than x_2 for any of the functions and it is better for at least one function:

$$\forall i \in \{1, 2, \dots, N_{obj}\}: f_i(x_1) \leq f_i(x_2) \quad (17)$$

$$\exists j \in \{1, 2, \dots, N_{obj}\}: f_j(x_1) < f_j(x_2)$$

The algorithm steps are as follows:

1. Initial population generation: At the first step, particles are initialized with random positions and velocities. In the considered case, the size and location of DSTATCOM and capacitors are generated in form of vectors as algorithm particles. The DSTATCOM reactive power is considered as a continuous variable. The considered capacitance is an integral multiple of the minimum base value. The locations of DSTATCOM and capacitors are positive integers.
2. Load flow and calculation of objective functions.
3. Determine the non-dominated solutions.
4. Store the non-dominated solutions in a repository.

5. Use the equations to update each particle. Considering that we have a set of optimal solutions, a leader should be chosen for each particle. In this step, the best position of each particle should be updated by comparing the new position to the best global position of each particle and selecting the dominant one as the new position. If none of them dominates, one will be chosen randomly.
6. In this step, the best position of each particle should be updated by comparing the new position to the best global position of each particle and selecting the dominant one as the new position. If none of them dominates, one will be chosen randomly.
7. After updating all the particles, store the non-dominated members of the current population in the repository.
8. Investigate the repository. Remove the dominated solution and keep the non-dominated solutions.
9. If the repository gets full, remove the extra solutions.
10. If the algorithm converges, the optimization process is over. Otherwise, go to step 5.
11. If the optimization process is over, select the non-dominated population as the Pareto front.

The Pareto front is composed of a number of optimal solutions. The distribution system designers and operators should select the final solution based on their knowledge and their requirements. Due to the inherent uncertainty in operators' decision, the fuzzy compromise technique can be of help in selection of the final solution.

C. Fuzzy compromise selection

In this method, a value will be attributed to the i^{th} objective function F^i for the k^{th} solution of the Pareto front as follows:

$$\mu_i^k = \frac{f_i^{\max} - f_i}{f_i^{\max} - f_i^{\min}} \quad \begin{matrix} f_i \leq f_i^{\min} \\ f_i^{\min} \leq f_i \leq f_i^{\max} \\ f_i \geq f_i^{\max} \end{matrix} \quad (18)$$

where f_i^{\min} and f_i^{\max} represent the maximum and minimum of i^{th} objective function among all Pareto front solutions.

For k^{th} solution, the fuzzy membership function μ^k can be calculated as follows. The solution with the maximum value of μ^k is the best solution for the problem.

$$\mu^k = \max_{k=1}^N \min_{i=1}^m \mu_i^k \quad (19)$$

I. SIMULATION RESULTS

To test the proposed method for optimal placement and sizing of DSTATCOM and parallel capacitors, the IEEE 33-node test feeder is employed. The feeder is presented in Fig.4 and its data is taken from [20].

Three different cases are considered. In *Case 1* the optimal size and location of DSTATCOM and capacitors are selected by applying the proposed method. In *Case 2* only the capacitors size and location are optimized, while *Case 3* only considers DSTATCOM. Fig. 5 shows the convergence trend of the employed MPSO algorithm for *Case 1*. Each axis of the figure is related to one of the considered objective functions. It can be seen that the optimization algorithm is well converged for all objective function. The obtained optimal location and size of the parallel capacitors and DSTATCOM for all three cases are presented in Table. 1.

For *Case 1*, Fig. 6 shows the network voltage profile before and after installation of parallel capacitors and DSTATCOM at selected locations and with selected sizes. The figure clearly shows the improved voltage profile of the network. Besides the voltage profile, voltage stability was one of the considered objectives. The voltage stability index presented in Fig. 7 indicates the methods success in improving the network voltage stability.

To better highlight the improvements, Table. 2, Table. 3 and Table. 4 compare some of the most common system performance measures for the three cases considered. The results clearly show that in all three cases, the installation of these devices has improved the system performance. However, the installation of both the parallel capacitors and DSTATCOM at selected locations and with selected sizes, has more impact on system performance improvements.

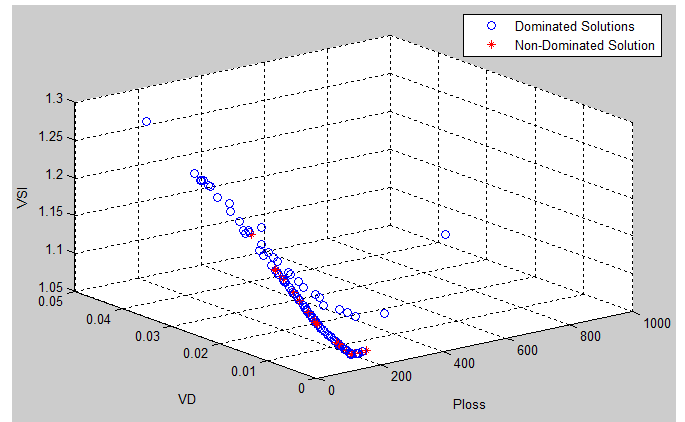


Figure 4. The convergence trend of MPSO for objective functions

TABLE I. THE SELECTED OPTIMAL SIZE AND LOCATIONS OF DSTATCOM AND CAPACITOR BANKS

Optimization results		Capacitor banks	DSTATCOM
Case 1	Nodes	7, 14	30
	Size (KVAR)	750, 450	792.48
Case 2	Nodes	6, 14, 29	----
	Size (KVAR)	300, 600, 900	----
Case 3	Nodes	----	7
	Size (KVAR)	----	1233

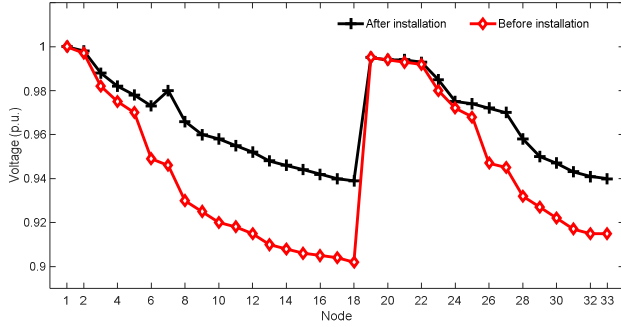


Figure 5. The network voltage profile before and after installation of the parallel capacitors and DSTATCOM

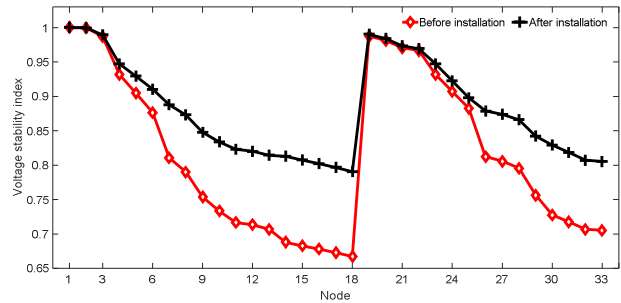


Figure 6. The voltage stability index before and after installation of the parallel capacitors and DSTATCOM

II. CONCLUSIONS

The problem of simultaneous optimal placement and sizing of DSTATCOM and parallel capacitors is of considerable importance, considering their ability in improving the networks performance. In this paper, the MOPSO algorithm is employed to solve the problem for a 33-node test feeder. The results indicate the applicability and good performance of the proposed method. They show that a combination of parallel capacitors and DSTATCOM has more impact on system performance improvements compared to using each individually. Installation of these devices in selected locations and with selected sizes, satisfies the considered objective functions in terms of decreasing the distribution networks power losses, improving the voltage profile and the voltage stability. Our studies show that the proposed method is fast, flexible and efficient, such that it can be used to simultaneously find the optimal size and location of various devices in distribution networks as a multi objective problem.

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TABLE II. THE SYSTEM PERFORMANCE MEASURES BEFORE AND AFTER INSTALLATION OF PARALLEL CAPACITORS AND DSTATCOM (CASE 1)

Performance measures	Before installation	After installation
Minimum voltage (p.u.)	0.9038 at node 18	0.9392 at node 18
Maximum voltage (p.u.)	0.997 at node 2	0.9978 at node 3
Active power loss (Kw)	210.99	111
Minimum voltage stability index (p.u.)	0.6671 at node 18	0.7902 at node 18

TABLE III. THE SYSTEM PERFORMANCE MEASURES BEFORE AND AFTER INSTALLATION OF PARALLEL CAPACITORS (CASE 2)

Performance measures	Before installation	After installation
Minimum voltage (p.u.)	0.9038 at node 18	0.928 at node 18
Maximum voltage (p.u.)	0.997 at node 2	0.996 at node 3
Active power loss (Kw)	210.99	142
Minimum voltage stability index (p.u.)	0.6671 at node 18	0.761 at node 18

TABLE IV. THE SYSTEM PERFORMANCE MEASURES BEFORE AND AFTER INSTALLATION OF DSTATCOM (CASE 3)

Performance measures	Before installation	After installation
Minimum voltage (p.u.)	0.9038 at node 18	0.922 at node 18
Maximum voltage (p.u.)	0.997 at node 2	0.995 at node 3
Active power loss (Kw)	210.99	153
Minimum voltage stability index (p.u.)	0.6671 at node 18	0.726 at node 18

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