**Jones GD, James DC, Thacker M, Perry R, Green DA.** Gait-Initiation Onset Estimation During Sit-to-Walk: Recommended Methods Suitable for Healthy Individuals and Ambulatory Community-Dwelling Stroke Survivors**. PLOSOne**

Author(s)

Gareth D Jones1,2

1Centre for Human and Applied Physiological Sciences (CHAPS), Shepherd’s House, Guy’s Campus, King's College London, London SE1 9RT, UK.

2Physiotherapy Department, 3rd Floor Lambeth Wing, St Thomas’ Hospital, Westminster Bridge Road, Guy's & St Thomas' NHS Foundation Trust, London, SE1 7EH, UK.

gareth.jones@gstt.nhs.uk

Darren C James3,[[1]](#footnote-1)

3Sport and Exercise Science Research Centre, London South Bank University, 103 Borough Road, London, SE1 0AA, UK.

jamesd6@lsbu.ac.uk

Michael Thacker1,2,[[2]](#footnote-2)

1Centre for Human and Applied Physiological Sciences (CHAPS), Shepherd’s House, Guy’s Campus, King's College London, London SE1 9RT, UK

2Physiotherapy Department, 3rd Floor Lambeth Wing, St Thomas’ Hospital, Westminster Bridge Road, Guy's & St Thomas' NHS Foundation Trust, London, SE1 7EH, UK.

michael.thacker@lsbu.ac.uk

Rhian Perry2

2Physiotherapy Department, 3rd Floor Lambeth Wing, St Thomas’ Hospital, Westminster Bridge Road, Guy's & St Thomas' NHS Foundation Trust, London, SE1 7EH, UK.

rhian.perry@gstt.nhs.uk

David A Green1,[[3]](#footnote-3)

1Centre for Human and Applied Physiological Sciences (CHAPS), Shepherd’s House, Guy’s Campus, King's College London, London SE1 9RT, UK

david.green@esa.int

File Description

Data from: Gait-Initiation Onset Estimation During Sit-to-Walk: Recommended Methods Suitable for Healthy Individuals and Ambulatory Community-Dwelling Stroke Survivors

Tab 1: All Data

These data consist of measured variables derived from Visual 3D software (C-Motion Inc., Germantown, USA) for all trials undertaken by 20 stroke subjects and 21 gender and age-matched healthy subjects performing 2 tasks (sit-to-walk [STW] and sit-to-stand [STS]) 5 times. Subjects began walking with their affected lower extremity (stroke group) or their non-dominant lower extremity (NonDom; healthy group). Column header abbreviations listed below.

Tab 2: All Data Healthy

These data consist of measured variables derived from Visual 3D software (C-Motion Inc., Germantown, USA) for all trials undertaken by 21 gender and age-matched healthy subjects performing 2 tasks (sit-to-walk [STW] and sit-to-stand [STS]) 5 times. Subjects began walking with their non-dominant lower extremity. Column header abbreviations listed below.

Tab 3: All Data Stroke

These data consist of measured variables derived from Visual 3D software (C-Motion Inc., Germantown, USA) for all trials undertaken by 20 stroke subjects performing 2 tasks (sit-to-walk [STW] and sit-to-stand [STS]) 5 times. Subjects began walking with their affected lower extremity. Column header abbreviations listed below.

Tab 4: Subject Characteristics

These data consist of anonymised subject characteristics.

AMT – Abbreviated Mental Test Score [1]

NEALDS – Nottingham Extended Activities of Daily Living Scale [2]

Rivermead - Rivermead Mobility Index [3]

Temporal Variable Abbreviations

|  |  |  |
| --- | --- | --- |
| **Variable** | **Descriptor** | **Details** |
| T0 | Light On | Instance of light-on |
| T1 | Trunk Movt Onset | Instance of whole-body-centre-of-mass (BCoM) velocity breaching resting threshold |
| T2 | BCoM Max Horiz Vel | Instance of whole-body-centre-of-mass (BCoM) peak horizontal velocity |
| T3 | Seat\_Off | Instance of seat-off |
| T4 | Sum\_GRFmax | Instance of peak vertical ground reaction force (GRF) |
| T5 | BCoM Max Vert Vel | Instance of whole-body-centre-of-mass (BCoM) peak vertical velocity |
| T6 | Upright  | Instance of first time whole-body-centre-of-mass (BCoM) reaches upright at peak vertical displacement |
| T7a | xGRFthresh | GI-Onset estimation method 1:Instance when summated force plates mediolateral (x-component, away from swing limb) GRF signal (%BW) breaches the group xGRF Threshold |
| T7b | maxSWINGvGRF | GI-Onset estimation method 2:Instance of maximum in swing limb force plate vertical (z-component) GRF signal (N) occurring between Movement-Onset and 1st Heel-Off events |
| T7c | xGRFmax | GI-Onset estimation method 3:Instance of local maximum summated mediolateral (x-component, toward the stance limb) GRF signal (N) occurring between Movement-Onset and 1st Heel-Off event |
| T7d | firstHEELoff | GI-Onset estimation method 4:Instance when swing limb calcaneal marker vertical velocity signal (m.s-1) breaches >0.0 for ≥8frames (133ms) after Seat-Off event |
| T7x | xGRFthresh\_Individual | Alternative GI-Onset estimation method 1:Instance when summated force plates mediolateral (x-component, away from swing limb) GRF signal (%BW) breaches the individual xGRF Threshold |
| T7y | Max\_Sum\_vGRF | Alternative GI-Onset estimation method 2:Instance of local maximum summated vertical (z-component) GRF signal (N) occurring between Movement-Onset and 1st Heel-Off event |
| T7z | FIRSTtoeOFF (Unload) | Alternative GI-Onset estimation method 3:Instance when swing limb vertical (z-component) GRF signal (N) <20N for ≥8frames (133ms) after Seat-Off event |

Other Abbreviations Used

| **Column(s)** | **Abbreviation** | **Details** | **Units** |
| --- | --- | --- | --- |
| W | SumxGRFmax\_MovOnset-Upright\_%BW | The maximum mediolateral GRF (xGRF) derived from the sum of the two force plates recorded between the movement-onset and Upright movement events as a percentage of body-weight (BW) in NewtonsUsed for calculating the individual and group xGRF thresholds | (%BW) |
| X | SumxGRFmax\_MovOnset-HO1\_%BW | The maximum mediolateral GRF (xGRF) derived from the sum of the two force plates recorded between the movement-onset and first heel-off (HO1) movement events as a percentage of body-weight (BW) in NewtonsUsed for calculating GI-onset using the xGRFmax method | (%BW) |
| Y | xGRFthresh\_Threshold\_Ind | The threshold value used for calculating GI-onset using the xGRFthresh\_Individual method | (N) |
| Z | xGRFthresh\_Threshold\_Group | The threshold value used for calculating GI-onset using the xGRFthresh method | (N) |
| AA | TransTime\_xGRFthresh | Transition time using GI-onset estimation method 1 (xGRFthresh) | (s) |
| AB | TransTime\_ maxSWINGvGRF | Transition time using GI-onset estimation method 2 (maxSWINGvGRF) | (s) |
| AC | TransTime\_ xGRFmax | Transition time using GI-onset estimation method 3 (xGRFmax) | (s) |
| AD | TransTime\_ firstHEELoff | Transition time using GI-onset estimation method 4 (firstHEELoff) | (s) |
| AE | Time\_FlexMom | Time between Movement-Onset and Seat-off (Flexion momentum phase time ) | (s) |
| AF | Time\_MovtOnset to S3 | Time between Movement-Onset and 3rd heel-contact (Step 3) | (s) |
| AG | Time\_Response | Time between Light-on and Movement-Onset (Response phase time) | (s) |
| AH | Time\_RisePhase | Time between Movement-Onset and Upright (Rise phase time) | (s) |
| AI | Max\_BCoM\_Mom\_Lat | Maximal whole-body-centre-of-mass (BCoM) momentum, mediolateral component (absolute value) during rising | (kg.m/s) |
| AJ | Max\_BCoM\_Mom\_Horiz | Maximal whole-body-centre-of-mass (BCoM) momentum, horizontal component (forward) during rising | (kg.m/s) |
| AK | Max\_BCoM\_Mom\_Vert | Maximal whole-body-centre-of-mass (BCoM) momentum, vertical component (absolute value) during rising | (kg.m/s) |
| ALAMAN | Max\_CoP\_xCoM dist\_S3Max\_CoP\_xCoM dist\_S2Max\_CoP\_xCoM dist\_S1 | Maximal horizontal distance between the centre-of-pressure (CoP) and the extrapolated-centre-of-mass (xCoM) during the 3rd step (S3), 2nd step (S2), and the 1st step (S1) | (m) |
| AOAPAQ | CoP\_xCoM\_Dist\_SeatOffCoP\_xCoM\_Dist\_TO1CoP\_xCoM\_Dist\_Upright | The horizontal distance between the centre-of-pressure (CoP) and the extrapolated-centre-of-mass (xCoM) at Seat-Off, 1st Toe-Off (TO1), and Upright | (m) |
| ARASATAU | S0\_StepWidthS1\_StepWidthS2\_StepWidthS3\_StepWidth | Step width (mediolateral distance between left and right calcaneal marker) at 1st Heel-Off (S0), 1st Initial-Contact (S1), 2nd Initial-Contact (S2), 3rd Initial-Contact (S3) | (m) |
| AVAWAX | S1\_StepLengthS2\_StepLengthS3\_StepLength | Step length (anteroposterior distance between left and right calcaneal marker) at 1st Initial-Contact (S1), 2ndt Initial-Contact (S2), 3rd Initial-Contact (S3) | (m) |
| AYAZBA | S1\_VelocityS2\_VelocityS3\_Velocity | Average whole-body-centre-of-mass (BCoM) velocity in anterioposterior direction (forward) during step 1 (S1; 1st Heel-Off to 1st Initial Contact), step 2 (S2; 1st Initial Contact to 2nd Initial Contact), step 3 (S3; 2nd Initial Contact to 3rd Initial Contact) | (m/s) |
| BB | S1-3\_Velocity | Average whole-body-centre-of-mass (BCoM) velocity in anterioposterior direction (forward) during steps 1 through 3 (1st Heel-Off to 3rd Initial Contact) | (m/s) |

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1. Corresponding Author [↑](#footnote-ref-1)
2. Present Address: School for Health and Social Care, London South Bank University, London,
United Kingdom [↑](#footnote-ref-2)
3. Present Address 1: European Astronaut Centre, Directorate of Human Spaceflight and Robotic Exploration Programmes (D/HRE), European Space Agency, Cologne, Germany
Present Address 2: KBRwyle GmbH, Albin Köbis Straße 4, Cologne, 51147, Germany [↑](#footnote-ref-3)