

1 Short Communication

2 **Loading rate and contraction duration effects on *in vivo* human**

3 **Achilles tendon mechanical properties**

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23

24 **Short title:** Achilles tendon mechanical properties *in vivo*



26 **Summary**

27 Tendons are viscoelastic, which implies loading rate dependency, but loading rates of  
28 contractions are often not controlled during assessment of human tendon mechanical  
29 properties *in vivo*. We investigated the effects of sustained submaximal isometric  
30 plantarflexion contractions, which potentially negate loading rate dependency, on the  
31 stiffness of the human Achilles tendon *in vivo* using dynamometry and ultrasonography.  
32 Maximum voluntary contractions (high loading rate), ramp maximum force contractions  
33 with 3s loading (lower loading rate), and sustained contractions (held for 3s) at 25%,  
34 50% and 80% of maximal tendon force were conducted. No loading rate effect on  
35 stiffness (25-80% max. tendon force) was found. However, loading rate effects were  
36 seen up to 25% of maximum tendon force, which were reduced by the sustained  
37 method. Sustained plantarflexion contractions may negate loading rate effects on tendon  
38 mechanical properties and appear suitable for assessing human Achilles tendon stiffness  
39 *in vivo*.

40

41 **Keywords:** Gastrocnemius muscle, M. triceps surae, tendon stiffness, tendon strain,  
42 muscle strength, ultrasonography

43

44

45 **Introduction**

46 Tendons transfer force generated by the muscles to the bones, leading to joint rotations  
47 and movement, and therefore, tendon mechanical properties can have a large impact on  
48 movement effectiveness. The mechanical properties of the *triceps surae* muscle-tendon  
49 unit play an important role in locomotion, with the muscles providing significant  
50 propulsive force during the push-off phase of gait and the tendinous structures storing  
51 and returning elastic energy to the joint (Biewener and Roberts, 2000; Roberts, 2002),  
52 thereby affecting the efficiency of movement (Hof *et al.*, 2002; Huang *et al.*, 2015;  
53 Lichtwark and Wilson, 2007; Pandy and Andriacchi, 2010). Specifically, the  
54 mechanical properties of the Achilles tendon (AT) are of interest, as the stiffness or  
55 slackness of the AT greatly influences the ability of the *triceps surae* muscle-tendon  
56 unit to contribute to forward propulsion during gait. The most common  
57 method currently for assessing human tendon mechanical properties *in vivo* is  
58 synchronous ultrasonography and dynamometry, originally proposed by Fukashiro *et al*  
59 (1995) and later further developed by Kubo *et al.* (1999), Maganaris and Paul (1999)  
60 and Maganaris (2002). However, one factor that may affect the accuracy of tendon  
61 mechanical properties assessment *in vivo* is tendon viscoelasticity.

62 Tendon viscoelasticity, which implies loading rate dependency (a viscous time-  
63 dependent property) of tendon tensile strain (Abrahams, 1967; Hooley *et al.* 1980;  
64 Fung, 1993), is generally accepted and has been shown in human lower limb tendons *in*  
65 *vivo* (Gerus *et al.*, 2011; Kusters *et al.*, 2014; Pearson *et al.*, 2007; Theis *et al.*, 2012).  
66 However, other studies have not found loading rate dependency in human tendons *in*  
67 *vivo* (Kubo *et al.*, 2002; Peltonen *et al.*, 2013). These differences in findings may be  
68 related to the tendon (AT or patellar) or tendon structure (tendon or aponeurosis)

69 analysed, due to differences in deformation characteristics between structures or tendon  
70 elongation tracking procedures, as well as other methodological differences, such as the  
71 duration and rate of loading used or the method used to account for joint movement on  
72 the measured tendon elongation during contraction (for a detailed overview of such  
73 methodological issues, see Seynnes *et al.* (2015)).

74 Many studies of *in vivo* tendon mechanical properties have employed ramped isometric  
75 contractions, with a gradual increase to maximum voluntary force over a number of  
76 seconds (*e.g.*: Arampatzis *et al.*, 2007b; Kubo *et al.*, 1999; Kubo *et al.*, 2000b; Kubo *et*  
77 *al.*, 2000a; Maganaris and Paul, 2002; Maganaris *et al.*, 2004; Reeves *et al.*, 2005;  
78 Seynnes *et al.*, 2009). However, if a set time (*e.g.* three seconds) is given to reach  
79 maximum force, the absolute loading rate may differ between participants of different  
80 strengths (Kosters *et al.*, 2014). One method that may negate such loading rate effects is  
81 to instead use isometric contractions held at multiple given submaximal force levels.  
82 This contraction method has recently been used in different forms to assess AT  
83 mechanical properties (Ackermans *et al.*, 2016; Farris *et al.*, 2013; Lichtwark *et al.*,  
84 2013; Obst *et al.*, 2016), but the method's effects on loading rate dependency have not  
85 been investigated.

86 The sustained method may negate loading rate dependency as it addresses the phase  
87 shift (due to the time-dependent viscous properties) of the reactive response of  
88 viscoelastic material (Meyers and Chawla, 1999). This can be illustrated using a simple  
89 Kelvin-Voigt model, comprised of a purely viscous damper and purely elastic spring  
90 connected in parallel (see examples of Kelvin-Voigt model application in biological  
91 tissue assessment in: Alkalay *et al.*, 2015; Kiss *et al.*, 2004; Tzschatzsch *et al.*, 2014).  
92 When an external stress is applied to the model, the spring deforms while the damper

93 acts against the deformation, causing a time delay in the deformation. After a certain  
94 time, the model reaches its final deformation, determined by the spring constant and the  
95 applied stress. As well as potentially negating loading rate dependency, a constant force  
96 held for a given time period potentially negates measurement error due to ultrasound  
97 sampling frequency or synchronization delays between ultrasound and force data,  
98 previously suggested by Finni *et al.* (2013) as limitations for measuring AT hysteresis  
99 *in vivo*.

100 Given the potential benefits of sustained isometric contractions on *in vivo* tendon  
101 mechanical property assessment, this study aimed to determine if sustained submaximal  
102 isometric plantarflexion contractions would negate potential effects of loading rate on  
103 AT stiffness measurements in comparison to traditionally used contractions (MVC and  
104 ramp contraction).

105

## 106 **Methods**

### 107 *Study Participants*

108 Ten male adults (mean[SD] age: 26.5[5.5] years) participated in this study. Volunteers  
109 with previous AT ruptures, AT injury within the last 12 months, or musculoskeletal  
110 impairments were excluded. The study was approved by the German Sport University  
111 Cologne ethical board and informed consent was obtained according to the Declaration  
112 of Helsinki.

113

### 114 *Experimental Setup and Procedure*

115 The experimental setup used in this study has been described previously in detail  
116 (Karamanidis *et al.*, 2016). Briefly, the participants were seated on a custom made

117 dynamometer with the knee of the dominant leg fully extended and the foot of the  
118 dominant leg positioned on the dynamometer foot plate perpendicular to the femur and  
119 tibia (see Fig. 1Ai). A custom made brace constructed using ski bindings was attached  
120 around the foot and the dynamometer foot plate to reduce any joint motion during  
121 contractions.

122 ***Insert Fig. 1***

123 The measurements began with a standardized warm-up of five minutes hopping and  
124 stretching, 2-3 minutes of submaximal contractions guided by TEMULAB software  
125 (Protendon GmbH & Co. KG, Aachen, Germany), and three maximal isometric  
126 contractions to precondition the tendon (Maganaris, 2003). Following this, participants  
127 completed three MVCs with a high loading rate, three ramp maximum force  
128 contractions with a three second loading time (guided by visual feedback provided by  
129 the software) resulting in a lower loading rate, and nine sustained contractions at the  
130 same lower loading rate (also with visual feedback), held three times for three seconds  
131 at 25%, 50% and 80% of the maximal tendon force ascertained during the MVC  
132 protocol. The order of the ramp and sustained contractions was randomized (MVC  
133 always first). The fact that MVC was always performed first was assumed not to affect  
134 the results as tendon preconditioning was conducted and no acute change in the  
135 properties would be expected as a result of further contractions within our protocol  
136 (Maganaris, 2003). Sufficient rest was given between contractions (approximately two  
137 to three minutes). For the MVCs, participants were instructed to produce as much force  
138 as possible, as fast as possible. Representative ankle joint moment-time curves from one  
139 subject across the three tasks can be seen in Fig. 1(C). All three contraction tasks were  
140 repeated on a second day with all participants and the data were pooled for the analysis.

141

142 *Assessment of Achilles Tendon Mechanical Properties*

143 The *triceps surae* mechanical properties of the dominant leg were assessed during  
144 isometric plantarflexion contractions by integrating dynamometry (using three strain  
145 gauge load cells [100Hz] placed at pre-defined positions on the foot plate; Fig 1Aii) and  
146 ultrasonography (Aloka  $\alpha 7$ , Tokyo, Japan). Eight light emitting diodes (four on the  
147 lower limb and four on the force plate; Fig. 1Ai & ii) were used as active markers,  
148 whose 2D trajectories were recorded by two digital high-speed cameras (15Hz; Basler,  
149 Germany) and tracked automatically by the TEMULAB software (Karamanidis *et al.*,  
150 2016). The resultant ankle joint moments were calculated using inverse dynamics  
151 following compensation for moments resulting from gravitational and compression  
152 forces (Arampatzis *et al.*, 2005; Karamanidis and Arampatzis, 2005). Reaction forces  
153 under the foot and their respective lever arms to the ankle joint centre were assessed as  
154 described previously (Karamanidis *et al.*, 2016). AT force (N) was calculated by  
155 dividing the ankle joint moment (Nm) by the AT moment arm (m). The AT moment  
156 arm was estimated as the perpendicular distance from the ankle joint centre of rotation  
157 to the AT (Scholz *et al.*, 2008). The *m. gastrocnemius medialis* (GM) tendon was  
158 examined using a 7.5MHz linear array ultrasound probe. The probe was placed  
159 longitudinally over the GM myotendinous junction with a black rubber band placed  
160 between the skin and the probe to determine any probe motion relative to the skin (as in  
161 previous work: Arampatzis *et al.*, 2007a; Arampatzis *et al.*, 2005). All recordings were  
162 saved at 73Hz. Tendon elongation was determined by manually tracking the GM  
163 myotendinous junction during loading (Fig. 1B). The effect of potential ankle joint  
164 angular rotation on the measured tendon elongation during contractions (Magnusson *et*



165 *al.*, 2001) was taken into account by multiplying the estimated AT moment arm by the  
166 ankle joint angular changes during contraction. In this way, the actual tendon elongation  
167 caused by the exerted tendon force could be estimated. Tendon elongation was  
168 analysed at 25%, 50% and 80 % of MVC for all three contraction types. Tendon  
169 stiffness was determined as the ratio of the increase in the calculated tendon force and  
170 the increase in the elongation from 25 to 80% of maximum tendon force (AT  
171 Stiffness<sub>25-80%</sub>). Additionally, a post hoc analysis of the slope of the force-elongation  
172 relationship from 0% to 25% of maximal tendon force was conducted (AT Stiffness<sub>0-</sub>  
173 <sub>25%</sub>; see Results and discussion section).

174

#### 175 *Statistics*

176 The data from the two different measurement days were pooled together. The data of  
177 three participants on day two were excluded due to measurement errors, leaving 17  
178 samples for the analysis. Normality was checked using the Shapiro Wilk test. Wilcoxon  
179 Signed Rank tests were used to assess loading rate differences between MVC and ramp.  
180 A two-way ANOVA with method (MVC, ramp and sustained) and normalized tendon  
181 force (25%, 50% and 80%) as factors was used to determine method and tendon force-  
182 related differences in AT elongation. One-way ANOVAs with contraction method as a  
183 factor were used to determine method-related differences in AT Stiffness<sub>25-80%</sub> and AT  
184 Stiffness<sub>0-25%</sub>. Homogeneity of variance was checked with Levene's test. Significance  
185 was set at  $\alpha=0.05$ . Analyses were performed using IBM SPSS Statistics (Armonk, NY:  
186 IBM Corp.).

187

#### 188 **Results**

189 The ankle joint moment loading rates during the MVC and ramp contractions were  
190 (mean and SD) 3181(2032) and 688(151)Nm/s, respectively (Fig. 2A; approximately  
191 79% MVC per second and 18% MVC per second, respectively). The Wilcoxon Signed  
192 Rank tests revealed significantly ( $P<0.001$ ) lower loading rates during ramp, compared  
193 to MVC. A two way repeated measures ANOVA with method and tendon force level as  
194 factors found significant method ( $F_{[1.5, 24]}=15.5$ ,  $P<0.001$ ) and tendon force ( $F_{[1.4,$   
195  $23]}=277.5$ ,  $P<0.0001$ ) effects on tendon elongation (Fig. 2B). *Post hoc* tests with  
196 Bonferroni corrections revealed significant differences for tendon elongation between  
197 SUS and both RAMP and MVC, as well as between RAMP and MVC, for all tendon  
198 force levels ( $P<0.01$ ; see Table 1). The one way ANOVA with method (MVC, ramp and  
199 sustained) as a factor found no significant effect on AT Stiffness<sub>25-80%</sub> (Fig. 2C; MVC:  
200 654[221]N/mm; ramp: 695[190]N/mm; sustained: 564[148]N/mm;  $F_{[2, 32]}=2.5$ ,  
201  $P=0.079$ ).

202 The fact that elongation, but not stiffness was significantly different between methods in  
203 the current study suggests that the change in elongation observed between methods  
204 occurred prior to the force levels used in this study (i.e. up to 25% of AT force) and that  
205 the difference in elongation remained constant between the methods thereafter, which  
206 agrees with our theory that the sustained contraction method accommodates the phase  
207 shift of the reactive response to applied force due to tendon viscoelasticity. Therefore, a  
208 *post hoc* analysis of the slope of the force-elongation relationship from 0% to 25% of  
209 maximal tendon force (AT Stiffness<sub>0-25%</sub>) was conducted in a similar manner to  
210 Lichtwark *et al.* (2013). A one way ANOVA with method (MVC, ramp and sustained)  
211 as a factor revealed a significant method effect on AT Stiffness<sub>0-25%</sub> (Fig. 2D; MVC:  
212 190[46]N/mm; ramp: 165[43]N/mm; sustained: 150[37]N/mm;  $F_{[1.5, 24]}=14$ ,  $P<0.001$ ).

213 *Post hoc* tests with Bonferroni corrections (see Fig. 2D) revealed significant differences  
214 in AT Stiffness<sub>0-25%</sub> between MVC and RAMP (P=0.0455), MVC and SUS (P=0.0002)  
215 and RAMP and SUS (P=0.0353).

216 ***Insert Fig. 2***

217

## 218 **Discussion**

219 In the current study, we aimed to determine if sustained submaximal isometric  
220 plantarflexion contractions would negate potential effects of loading rate on AT  
221 stiffness measurements in comparison to traditionally used contractions (MVC and  
222 ramp contraction). Loading rate dependency was seen for AT elongation, as fast (MVC:  
223 mean of 3181Nm/s) and slower (ramp: 688Nm/s) loading rate contractions led to  
224 differences in elongation (Fig. 2B and Table 1). However, an effect of loading rate was  
225 not observed in AT stiffness, as no significant differences were found between MVC  
226 and ramp contractions. In order to further investigate the change in tendon elongation  
227 across methods, we conducted a *post hoc* analysis of AT Stiffness<sub>0-25%</sub> (Fig. 2D) in a  
228 similar manner to Lichtwark *et al.* (2013). We were able to confirm that, at this region  
229 of the force-elongation relationship, significant differences in the slope could be seen,  
230 confirming loading rate dependency (Fig. 2D; MVC vs. RAMP) and at least a partial  
231 negation of loading rate dependency using the sustained contraction method (Fig. 2D;  
232 SUS vs. MVC and SUS vs. RAMP). This finding seems to support our suggestion that  
233 the sustained contraction method accommodates the phase shift of the reactive response  
234 to applied force due to tendon viscoelasticity.

235 Despite its widespread use, a number of methodological challenges exist that may  
236 preclude the precise assessment of tendon mechanical properties *in vivo*, as recently

237 highlighted by Seynnes *et al.* (2015). Synchronization of ultrasound, dynamometer and  
238 computer systems is one of these challenges. Synchronization can introduce error,  
239 whereby computer processing time or the typically lower sampling frequency of  
240 ultrasound devices may introduce lag in comparison to the higher frequency force  
241 measurements (6). This has been demonstrated experimentally in the AT *in vivo* by  
242 Finni *et al.* (2013), where an artificial desynchronisation between force and ultrasound  
243 recordings (one ultrasound frame; 10ms) resulted in a 4-5% change in calculated AT  
244 stiffness, although the change was not as high when compared to AT hysteresis (9-10%  
245 change). Importantly, *in vivo* methodologies are limited to the loading rates achievable  
246 during voluntary contractions, which are much lower and less controllable than those  
247 possible in *in vitro* setups. The wide range in achieved loading rates during the MVCs  
248 in the current study (Fig. 2A) demonstrates the large variation between young, healthy  
249 participants in their ability to achieve high loading rates *in vivo*. The sustained  
250 contraction method on the other hand, as outlined in the current study, may well be a  
251 solution for negating measurement error due to ultrasound sampling frequency or  
252 synchronization delays between ultrasound and force data, and appears to negate the  
253 effects of loading rate dependency on the mechanical properties of the AT. With this in  
254 mind, it is worth noting that the variability in AT Stiffness<sub>25-80%</sub> was lowest for the  
255 sustained contraction (Fig. 2C). Additionally, image processing and digitizing time is  
256 greatly reduced. Finally, while not currently conducted, electromyography signals may  
257 be more repeatable when taken during sustained contractions due to the longer  
258 observation window (Rainoldi *et al.*, 1999), which would benefit the examination of the  
259 effect of tibialis anterior co-activation on the resultant ankle joint moment during  
260 plantarflexion contractions (Mademli *et al.*, 2004).

261 When interpreting the current findings, it is important to note that the AT force is  
262 estimated *in vivo* using the resultant ankle joint moment. As a result, the influence of  
263 synergistic and antagonist muscles, which may differ between different loading rates  
264 and contraction types, have not been accounted for. This, in turn, may lead to errors in  
265 the tendon force-elongation relationship calculation, potentially reducing the ability to  
266 detect small changes in tendon stiffness between loading rates and contraction types.  
267 That being said, the effect of co-contraction of the tibialis anterior, for example, is  
268 relatively low in young healthy subjects (accounting for co-contraction of the tibialis  
269 anterior results in approximately a 4% increase in the maximal ankle joint moments  
270 generated by the *triceps surae* muscle-tendon unit during an MVC; Arampatzis *et al.*,  
271 2005) and therefore, a large effect on the force-elongation relationship would not be  
272 expected. It is also noteworthy that it was not possible to measure the loading rates  
273 during the sustained contractions in our protocol; however, these should have been  
274 similar to the ramp rates, as the same guidance software and settings were used. Finally,  
275 AT Stiffness<sub>0-25%</sub> does not represent true tendon stiffness at this tendon force level due  
276 to the non-linearity of the force-elongation relationship and is only used to give an  
277 indication of changes in the slope of the force-elongation relationship at the different  
278 regions in general (Lichtwark *et al.*, 2013). Regarding the difference in stiffness results,  
279 it is important to note that the time under load in the 0 to 25% period differed more  
280 between the methods than during the 25 to 80% period and that the magnitude of the  
281 change in tendon elongation was greater in the 0 to 25% in comparison to the 25 to 80%  
282 region for all contraction durations (MVC: 2.8mm vs. 1.9mm; ramp: 3.3mm vs. 1.6mm;  
283 sustained: 3.4mm vs. 2mm). Due to lower absolute elongation of the tendon in the

284 higher region of the force-length relationship, small differences between methods are  
285 more difficult to detect due to the potential measurement error of the ultrasound method.

286 In conclusion, the current results indicate that tendon stiffness results do not greatly  
287 differ between MVC, ramp and sustained plantarflexion contractions. Within the range  
288 of loading rates used in this study, which represent those experienced in daily life, no  
289 measureable effect of loading rate on stiffness measurements was found. However,  
290 loading rate effects were seen in the force-elongation relationship up to 25% of  
291 maximum tendon force, which appeared to be reduced by the sustained contraction  
292 method. Therefore, sustained plantarflexion contractions may negate potential loading  
293 rate effects on the force-elongation relationship of the human AT *in vivo* and represent a  
294 valid alternative to MVC and ramp contractions.

295

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302

### 303 **Conflicts of interest**

304 KDO, PK and KK have equity in Protendon GmbH & Co. KG, whose software was  
305 used for the data processing and analysis in this study. No other authors declare any  
306 conflicts of interest.

307



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424

425 **Tables**

426 **Table 1.** Bonferroni multiple comparisons tests for Achilles tendon elongation during  
 427 MVC, ramp and sustained contraction methods

Tendon Force Level [% max.]	Contraction Methods	Mean		Adjusted P Value
		Difference [mm]	95% Confidence Intervals of Differences	
25	MVC vs. RAMP	-0.9663	-1.421 to -0.5115	<0.0001
	MVC vs. SUS	-1.532	-1.987 to -1.077	<0.0001
	RAMP vs. SUS	-0.5658	-1.021 to -0.1109	0.0097
50	MVC vs. RAMP	-0.8324	-1.287 to -0.3776	<0.0001
	MVC vs. SUS	-1.623	-2.078 to -1.169	<0.0001
	RAMP vs. SUS	-0.791	-1.246 to -0.3362	0.0002
80	MVC vs. RAMP	-0.7165	-1.171 to -0.2617	0.0008
	MVC vs. SUS	-1.847	-2.302 to -1.392	<0.0001
	RAMP vs. SUS	-1.13	-1.585 to -0.6755	<0.0001

428

429

430 **Figure Legends**

431 **Fig. 1.** Experimental setup and methodology. **(A) i:** Lateral camera view of the  
432 participant and dynamometer setup; **ii:** position of the foot and strain gauge load cells  
433 (black circles) on the dynamometer foot plate; **(B):** examples of myotendinous junction  
434 tracking to examine tendon elongation using the ultrasound images at rest and at 25%,  
435 50% and 80% of MVC force. (A) and (B) adapted from Karamanidis *et al.* (2016). **(C):**  
436 Representative plantarflexion ankle joint moment data of one subject for an isometric  
437 maximum voluntary contraction with a high loading rate (MVC), an isometric ramp  
438 contraction (RAMP) and isometric sustained contractions (SUS). The black circles  
439 represent the time points when the 25%, 50% and 80% MVC measures were taken for  
440 each method.

441

442 **Fig. 2.** *Triceps surae* muscle-tendon unit mechanical properties during maximum  
443 voluntary contractions with a high loading rate (MVC), isometric ramp contractions  
444 with a three second loading time (RAMP) and isometric sustained contractions (SUS) at  
445 force levels of 25%, 50% and 80% of maximal tendon force. Results are medians with  
446 error bars of the 95% confidence intervals. \*, \*\* and \*\*\* represent significant  
447 contraction method differences ( $P < 0.05$ ,  $P < 0.01$  and  $P < 0.001$ , respectively). **(A):** Ankle  
448 joint moment loading rates during the MVC and RAMP contractions. **(B):** Achilles  
449 tendon elongation at 25%, 50% and 80% of maximal tendon force during MVC, RAMP  
450 and SUS contractions at each force level. Significant method ( $P < 0.001$ ) and tendon  
451 force level ( $P < 0.0001$ ) effects were found. **(C):** Achilles tendon stiffness determined  
452 from 25% to 80% of maximal tendon force during MVC, RAMP and SUS contractions.

453 **(D):** *Post hoc* analysed Achilles tendon stiffness determined from 0% to 25% of  
454 maximal tendon force during MVC, RAMP and SUS contractions.